

TRAFFIC PULSE-ROADWAY CONTROL SYSTEM.

Prof. Indu K S,

Neha R, Shreya Indoria, Shreya V ,Sowmya R

The Oxford College Of Engineering,

Bengaluru-68

Abstract:

Rapid transit and transportation networks are essential to any country's economic progress. Long wait times, lost fuel, and financial losses are the outcomes of poor management and traffic congestion. For the sake of national development, a quick, affordable, and effective traffic control system is thus absolutely essential. In many nations, keeping an eye on and managing urban traffic is turning into a significant issue. The Traffic Monitoring Authority needs to come up with innovative ways to solve this issue because there are more and more cars on the road. Using automation and intelligent control techniques is one option to enhance the current transportation system's traffic flow and safety. Efficient and quick congestion relief is the aim. The project includes sound sensors that can recognize emergency cars as they approach in order to improve emergency vehicle detection. By prioritizing and streamlining emergency vehicle traffic at signalized junctions, this cutting-edge feature seeks to enhance overall traffic management and response times. Additionally, the concept has a novel element for pedestrian safety: when a signal changes from red to orange or orange to green, a dynamically triggered block is deployed. By erecting a barrier that guarantees pedestrians are securely clear of traffic before crossing, this creative solution seeks to improve pedestrian safety.

Keywords:

Traffic jams, traffic surveillance, automation, and clever control techniques, Changes in signals, sound sensors, emergency vehicle detection, quicker reaction times, barriers, and pedestrian safety.

I. Introduction:

The future of intelligent traffic control will be greatly impacted by the growing number of road users and the finite resources offered by the current infrastructures. Heavy traffic at a crossroads may cause traffic congestion. There are numerous traffic management strategies available to prevent congestion. However, no method is flawless on its own since real-world conditions are almost always changing, and systems must adjust to these ever-changing conditions. In order to adapt to constantly shifting real-time traffic circumstances, we have attempted to give some self-adjusting traffic management strategies.

According to the amount of traffic on the road, this method assigns time to each lane's traffic signal, with priority given to ambulances. Additionally, we can designate a signal break in a specific lane. To prevent annoyance, an LCD is employed to show the obstruction detection message when there is one. The truth is that both the city's population and the quantity of cars on the road are growing daily. The necessity for street, highway, and traffic control is becoming more and more important as the population of metropolitan areas grows and so does the number of cars. The methods

employed for traffic management are the primary cause of the traffic issue of today. Traffic is inefficient because the current traffic management system places little attention on real-time traffic scenarios.

The goal of this project, which has been carried out with the Python Open CV program, is to avoid severe traffic congestion. Additionally, image processing techniques are incorporated in the project's implementation. Initially, a camera records video of a lane. After that, the traffic density is determined by processing these photos effectively. The controller will instruct the traffic LEDs to display a specific time on the signal to manage traffic based on the data it has collected from Mat Lab.

II. Literature survey:

Our goal is to "Develop a Smart Traffic Light Control System with Real Time Monitoring- IEEE 2020" in this review paper. Writers: Paulo Manera, Fernando Luiz, Denis Garcez Da Luz, and Leandro Tiago Pinto De Oliveira Methods: . By providing an all-inclusive control system for different types of urban intersections, the aim is to contribute to improving traffic signals. In this study, the development of a wirelessly communicative traffic control system with remote control capabilities is presented. It describes the many kinds of traffic light junctions, the electronic gadget and wireless network that are utilized, and the ways in which the wireless traffic lights at an intersection communicate with one another. This communication protocol relies on the exchange of packets and messages between the "end device" and the "coordinator (gateway) network."

A Beagle Bone Black with Linux integrated is used by the system coordinator to handle query management in the local network database. The report also presents the outcomes of real-world testing and discusses potential avenues for further research. Benefits The article highlights the advantages of implementing wireless communication technology, which makes it

easier to install more traffic lights and permits real-time traffic light operation monitoring. Cons: Conventional traffic signal systems cause traffic congestion and time waste since they have a static time base and do not account for the flow of vehicles on the route.

Inside [2] The author of this dissertation looks into. Three noteworthy contributions are made. In order to extract features of bi-directional traffic flow in scenarios with intense traffic, a unique spatio-temporal counting feature (STCF) is first presented that takes into account the bi-directional traffic flow as a whole. This method is not the same as the conventional approach to the LOI vehicle counting problem, which is to track and identify individual vehicles. Second, instead of using a multi-target tracking procedure to observe and count every vehicle, a counting network called the counting Long Short-Term Memory (cLSTM) network is developed to analyse bidirectional STCF properties and count vehicles in subsequent video frames.

Finally, an estimating model is constructed to estimate traffic flow parameters such as volume, density, and speed. Experiments on the UA-DETRAC dataset and recorded videos show that the proposed vehicle counting approach operates faster and more accurately than the tested representative LOI counting methods. Furthermore, the suggested framework has real-time traffic flow parameter estimation capabilities, including volume, density, and speed. Benefits does away with the requirement for complex tracking methods. We introduce a tailored cLSTM network intended for efficient car counts. Cons: Not all of the cLSTM network's intricacy is explained. Finally, an estimating model is constructed to estimate traffic flow parameters such as volume, density, and speed. The recommended vehicle counts is supported by tests done with the UA-DETRAC dataset and movie recordings.

In[3] In this essay, the writer highlights This paper proposes the use of IoT to design a dynamic traffic control system based on congestion levels in order to address the previously mentioned problem. Using ultrasonic sensors to measure traffic congestion at intersections in real time, it controls the length of traffic signals. The development of this project is divided into three stages: hardware implementation, IoT-based system development, and simulation and logic development. The initial step of the simulations is carried out in Proteus, and the outcomes are presented in four scenarios: regular operations, low level congestion, medium level congestion, and high level congestion. Benefits By adjusting traffic lights in real time, the device reduces traffic congestion. Cleaner Air: It makes an effort to lessen pollutants and create a cleaner atmosphere by reducing congestion

Cons: depends on a reliable internet connection; in the event that it falters, the system might not work as intended. Due to the expense of building the IoT network and purchasing equipment, getting started could be expensive.

Within [4] The project's main objective is to use image processing, infrared sensors, and the Internet of Things to dynamically operate the traffic control system and increase efficiency. The goal of traffic management automation systems on the market is to computerize traffic lights. These systems use many technologies, such as GSM and NFC, to control the light (red, yellow, or green) on a periodic schedule. NFC focuses on the fundamental functions of an electrical switch. Our research aims to offer an automated IRsense-based solution that enables traffic signals to dynamically change from red to yellow to green. For this study, we intend to create a "Proof-of-Concept" project for a single junction that combines IR sensors, traffic lights, a Wi-Fi transmitter, and a Raspberry Pi microcontroller. The Raspberry Pi controller receives the Wi-Fi transmitter's

transmission of the sensed data obtained from the IR sensor. This compilation allows it to dynamically change the red signal's time, and it notifies the user when the signal is about to change as they travel. Our project's goal is to build an automated traffic control system that can allocate time in response to an infrared sensor signal. The market's traffic management automation systems work to computerize traffic signals and change their color from red to yellow to green on a regular basis. focuses on the fundamental functions of an electrical switch while utilizing a variety of technologies, such as GSM (Global System for Mobile Communication), NFC (Near Field Communication), etc. The main drawback of employing this kind of technology is having to wait a long time for the signal. Long-lasting congestion is created close to the signal area because the side with fewer cars or no cars is divided at the same time as the other sides with more crowded cars. On the other hand, there is a great possibility that this congestion will disappear or become less complicated for drivers by utilizing the dynamic traffic strategy. One of the main shortcomings of the current approach is that it only adjusts the traffic controller in a clockwise fashion without taking traffic density into account. The traffic density is computed, and the timer display is dynamically adjusted. This major advantage rules out the happening of 'unwanted wait' for the vehicles in the more crowded region.

Within [5] It is possible to program this system with crucial criteria that will allow it to make decisions for intelligent, automatic traffic light control. Additionally, the suggested system is made to accept data via active RFID technology regarding any emergency case. Emergencies include the deaths of presidents, premiers, and ambulances, which necessitate the automatic opening of the road for traffic. Consequently, the system will ensure traffic flow in emergency situations as well as on major

thoroughfares and roadways that need continuous flow of traffic, all while maintaining normal traffic flow on regular streets based on traffic density and time of day. Additionally, the suggested system can be adjusted to function automatically in the absence of human intervention or to permit human intervention under specific conditions. This study presents an intelligent traffic management and control system for cross-roads. By implementing an intelligent algorithm based on calculating priorities that indicate the total determined relative weight of a certain direction in a cross-road traffic flow, the suggested method seeks to alleviate traffic jams and create traffic flow in city streets. The system can identify emergency vehicles, such as ambulances, by utilizing the driver's mobile device or RFID technology. It can then arrange traffic to accommodate these emergency vehicles. This proposed system needs to be applied first on experimental traffics, then to be generalized on all cities streets.

Within [6] The traffic flow aids in management and control, particularly during periods of heavy traffic. It displays the status of the traffic at predetermined intervals. In this study, we suggest a vehicle counting traffic surveillance system. The suggested approach consists of five steps: vehicle counting, blob detection, blob analysis, blob tracking, and background subtraction. A vehicle is categorized via blob analysis, where it is modelled as a rectangular patch. The outcomes of the experiment demonstrate that the suggested method can deliver practical and real-time data for traffic surveillance. The traffic surveillance system has been the subject of much research in recent years due to its ability to yield valuable information including traffic flow density. The number of vehicles in a specific time frame, the average speed of traffic, and the length of the queue. More sensors are typically needed for the traffic monitoring system. A push button for measuring pedestrian

demand, loop detectors for detecting vehicle presence at a specific location, magnetic sensors (magnetometers), radar sensors, microwave detectors, and video cameras are some examples of common traffic sensors. The following module pipeline was used to analyse traffic videos: (1) background subtraction; (2) blob detection; (3) blob analysis; (4) blob tracking; and (5) vehicle counting. The system has been implemented in C++ in this paper. With a dual core CPU operating at 2.4 GHz, the machine can handle about 25 frames per second. As a result, it offers a method for identifying and tallying moving automobiles in traffic situations. For the same, the virtual loop-based approach is employed. However, the system cannot identify different kinds of vehicles. It might be applied to categorize each detector so as to enhance the statistical function. The findings demonstrate that the suggested system can deliver relevant and timely data for traffic surveillance, which is then utilized to manage traffic.

Within [7] In this study, a new method for controlling traffic at connected intersections is presented. The proposal suggests using a local fuzzy-logic controller (FLC) deployed at every intersection to determine the green period for every phase of a traffic-light cycle through dynamic programming (DP). In order to expand structured control beyond a single junction, coordination characteristics from the neighbouring junctions are also considered. This study looks at a realistic way to make it possible to easily implement coordination amongst junctions, rather than aiming for the absolute optimization of traffic delay, all the while trying to minimize delays, if at all possible. According to the simulation results, there is a significant reduction in the average delay per vehicle, especially when the traffic demand surpasses the capacity of the junction. Traffic congestion only gets worse as the population increases. Even building new roads doesn't necessarily

make a big difference. There is limited leeway for city planners to innovate in order to meet the demand for road traffic that is only growing. However, one practical way to reduce congestion is to make the most of the current infrastructure's capacity. The author of this study examines the approaches and tactics for managing traffic on roads. This coordinated control is based on a local fuzzy-logic controller (FLC) that has been created for specific junctions. The performance of this decentralized traffic control with DP junction coordination is demonstrated by applying it to a basic two-junction network that experiences a range of traffic needs.. In this network, the local junction controllers are the intended FLCs. The road network's geographic knowledge is not necessary for the controller, which has a straightforward architecture. For the local control and learning processes, they use fuzzy logic and genetic algorithms (GA), respectively.

In [8], traffic congestion has grown to be a significant issue in all major cities worldwide. An intelligent traffic control system is necessary to guarantee a dependable transportation network. Getting traffic data is the first step towards doing that. Several techniques can be used to get traffic information. However, due to their increased intelligence and ease of maintenance, image processing techniques have become a very important and promising area of study to address traffic-related issues in recent years. The majority of the effort is counting the number of vehicles on the road and detecting their edges. The quantity of traffic congestion increases with the area of the road taken up by automobiles. In this manner, the traffic density can take into consideration all types of vehicles. The suggested methodology uses this traffic data to automatically regulate the traffic signals in a sequential fashion based on the volume of traffic on the road. Rather than counting the number of vehicles on the road in terms of traffic density, the suggested method estimates the

total area occupied by vehicles on the road. Depending on the overall traffic density of all the roads at the intersection, a variable traffic cycle is chosen. Each road is given a weight based on the traffic density, and the overall traffic cycle is weighted. In this manner, a traffic signalling system that is intelligence-based might be created. The problems with the conventional signalling system can be solved by using the suggested solution. This model might be expanded to include a large number of connected traffic intersections, with the traffic density at each intersection being used to modify the time allocation of neighbouring intersections. Emergency situations are not taken into account in this project, so when it fails, a manual method must be used in place of the smart traffic system. Some adjustments can be made to solve this issue.

III. Problem statement:

The Traffic Light System is the mainstay of the current traffic control technologies. Each phase is given a numerical number that determines how long the green lights will stay on different lanes. This strategy, however, is ineffective since it doesn't adjust dynamically to traffic circumstances, which frequently results in green lights being activated in empty lanes, wasting resources and causing congestion. An other method collects traffic data using sensors, which enables more flexible management of traffic signals according to current circumstances. But this approach's efficacy is constrained by how precise and comprehensive the sensors' data can be. The main objective is to create a reliable traffic management system that dynamically allots time to each lane in accordance with the traffic density of that lane in order to optimize traffic flow. In addition, the system is designed to give priority to lanes in when emergency vehicles, such as ambulances, are present in order to facilitate quick traffic flow and perhaps save lives. The proposed system can

optimize traffic flow by incorporating sophisticated algorithms and real-time data processing methods to automatically modify traffic signal timings, thereby reducing traffic jams, boosting security, and increasing overall effectiveness. This all-encompassing strategy takes emergency scenarios and traffic density into account, guaranteeing efficient traffic control adapted to the particular requirements of each lane and the larger transportation network.

IV. Proposed system:

By using state-of-the-art image processing methods, the proposed system seeks to transform traffic signal control. The first step in the procedure is picture acquisition, wherein cameras placed strategically at important intersections record live video of the flow of traffic. These pictures are the input for the system's later phases. Subsequently, image enhancement techniques are employed to enhance the clarity and quality of the obtained images, guaranteeing maximum visibility and precision for subsequent processing. Preprocessing techniques are used to further improve the photos by eliminating noise and extraneous details and emphasizing important elements like roads and cars. The use of machine learning and image processing methods to implement vehicle density monitoring is the main novelty.

. Through analysis of the processed photos, the system is able to provide useful information on traffic conditions, such as the precise number of vehicles in each lane. The traffic signal control mechanism uses the values it receives from the OpenCV Python library to function after receiving this real-time data. By using complex algorithms, the system prioritizes lanes with higher vehicle densities to improve traffic flow and dynamically modifies traffic signal timings in response to shifting traffic patterns. An pedestrian safety hump has also been implemented to guarantee

pedestrian safety. It will rise once the traffic signal displays the read signal. Through this comprehensive approach, the proposed system offers a dynamic and adaptive solution to traffic management and enhancing the safety of pedestrian, addressing the limitations of traditional methods and paving the way for more efficient and responsive traffic control systems. By harnessing the power of image processing and machine learning, it promises to revolutionize urban transportation networks, enhancing safety, reducing congestion, and improving overall traffic efficiency.

V. Methodology:

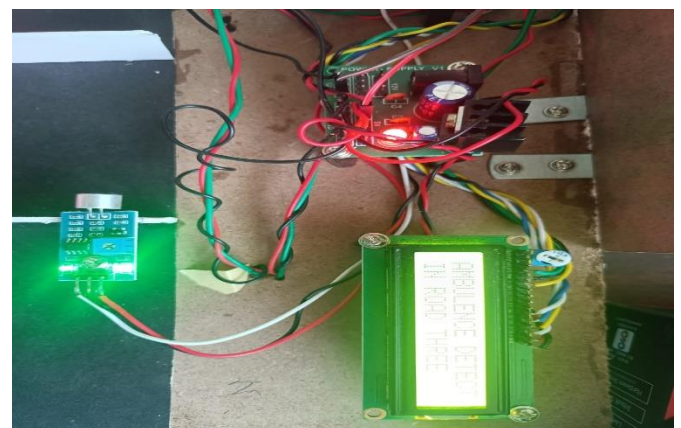
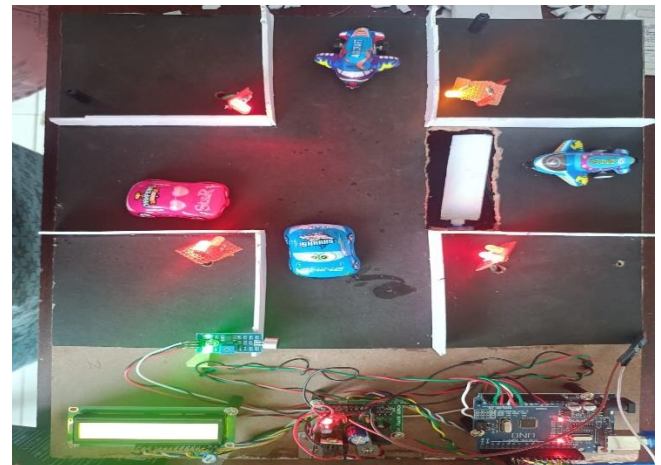
Live video input is received by WEB CAM via PYCHARM (OPENCV). Using the Arduino IDE, code is created to configure the DC motors. Transmit the Python data to the board and receive the same data back using DC motors. Here, we suggest an Intelligent Traffic Control [5] system that makes use of image processing and uses cameras placed along traffic lights to detect vehicles. A rectangular graphical entity is called an image. The smallest element in an image is a pixel; picture elements deal with complicated processes, image enhancing methods, and image compression, among other things. These processes, which include brightening, blurring, and sharpening, are used to improve photographs. It's a form of signal processing where the input signal is our image. An picture or an image's parameters are the output. There are certain backdrop restrictions that must be followed in order to correctly identify the hand palm with the least amount of noise in the image. One of the two main directions that the robot can move is forward or backward. Taking pictures of the frames: Images of roads that indicate traffic flow are taken by cameras. Since cameras are less expensive than electronics and sensors, image processing is both advantageous and cost-effective. We employ a method where the referred image and the acquired image are compared, and

different image processing techniques are used to obtain the desired outcome. Determining the ideal threshold value is crucial for image morphology. Erosion [2] and Dilation Perception of color are the operations in mathematical morphology. Three types of sensitivity are identified: green, red, and yellow. Given that we know these are the three commonly used colors, we can create any color by combining them. Since each pixel has a unique R-G-B parameter, we can take each one into consideration to produce a reflected single color when converting an R-G-B value to gray. To get results that are more appropriate, image augmentation is necessary. A group of mathematical techniques known as "edge detection" look for locations in an image where there are abrupt changes in brightness, discontinuities, or noise. The brightness value fluctuates according on the color. Green is the most vivid color. The yellow image is blurry, while the red image is noisy. Counting the automobiles Arduino will be used to process the data that was received via OPEN CV Python. Dynamic Traffic Signal Switching: The traffic signal is switched based on the number of vehicles on either side of the road. If there are more vehicles than there are, the signal is given to that side of the road; otherwise, regular static signal switching occurs. Emergency Vehicle Detection: Using sound sensors, if an emergency vehicle is found during this procedure, that road junction will be given precedence. In the event that there are emergency vehicles on both sides of the road, the priority of those vehicles will be determined by their respective counts. Servo Drives.

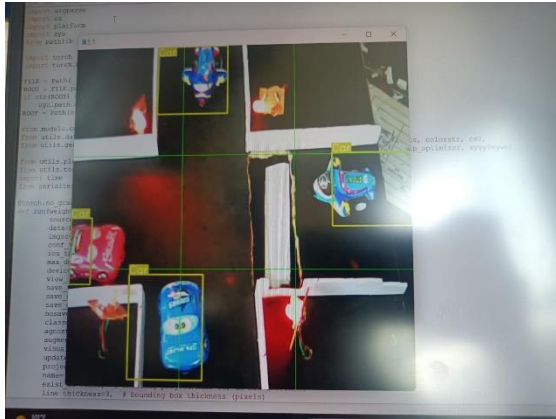
VI. Expected outcome:

Through the implementation of a dynamic signal switching mechanism utilizing real-time image detection, the project aims to optimize traffic flow in dense urban environments by employing advanced image processing techniques. The expected

result is an efficient and rapid alleviation of congestion. Additionally, the integration of sound sensors for emergency vehicle detection is poised to enhance the prioritization and streamlined passage of emergency vehicles through signalized intersections, contributing to quicker response times and overall improved traffic management during emergencies. The novel pedestrian safety feature, involving a dynamically activated block during signal transitions, is anticipated to enhance pedestrian safety by creating a barrier that ensures pedestrians are safely clear of traffic before crossing. The project's success will be gauged through tangible improvements in traffic flow, emergency vehicle prioritization, and pedestrian safety, validated through comprehensive real-world testing and data analysis.



When an ambulance is being detected it is being displayed in the LCD with the indication on which road the ambulance or emergency vehicle is being detected.



The car on each road is being detected and a pedestrian safety hump is being used which will be raised whenever the pedestrian will be crossing the road i.e. whenever the red light is being displayed. This we ensure that accident is prevented and pedestrian is also safe.

VII. Conclusion

This project introduces a dynamic traffic signal system with real-time image detection, aiming to enhance traffic flow, emergency vehicle prioritization, and pedestrian safety in dense urban areas. The implemented features show promise in efficiently alleviating congestion, improving emergency response times, and creating safer pedestrian crossings. The project's outcomes highlight potential advancements in urban traffic management, with implications for more responsive and secure transportation systems. Further evaluation and validation will provide valuable insights into the practical impact of these innovations on real-world traffic scenarios.

With the help of this project, the traffic problem can be resolved quickly. Each signal's timing can be automatically changed in real time based on the traffic density. In an emergency, it will also make way for the fire department and ambulance, and it will assist the general people in making decisions that will enable them to get at their destination on time by employing the auto-routing approach. It demonstrates that it can lessen traffic jams

and prevent time wasted by a green signal on a deserted road. Because it makes use of actual traffic photos, it is also more reliable in identifying the presence of vehicles. Compared to those systems that depend on the identification of the metal composition of the car, it performs far better because it visualizes reality.

Although the method is good overall, it still has to be improved in order to obtain 100% accuracy. The study demonstrated that image processing is a more effective method for managing the traffic light's status change. It demonstrates that it can lessen traffic jams and prevent time wasted by a green signal on a deserted road. Because it makes use of actual traffic photos, it is also more reliable in identifying the presence of vehicles. It works far better than other systems that depend on detecting the metal content of the automobiles since it visualizes reality.

VIII. References

1. An Automated Vehicle Counting System Based on Blob Analysis for Traffic Surveillance, IEEE-2020

<https://www.academia.edu/download/44329590/IPC4516.pdf>

2. "Coordinated Road Junction Traffic Control by Dynamic Programming" by Tsin Hing Heung, IEEE Intelligent Transportation Systems Conference, 2007, pp. 678-683. R

https://www.researchgate.net/publication/3427932_Coordinated_Road-Junction_Traffic_Control_by_Dynamic_Programming

3. Intelligent Traffic Signalling System" by Ch. Jaya Lakshmi S. Kalpana, IEEE Trans. Intell. Transport. Syst., vol. 1, no. 2, pp. 119-130, June 2002

https://www.researchgate.net/publication/318474769_Intelligent_traffic_signaling_system

4. Dynamic Traffic Management System Using Infrared Red(IR) and Internet of Things (IoT) by Paul Jasmine Rani, Khoushik Kumar, IEEE transport system conference, June 2016

https://www.researchgate.net/publication/322585817_Dynamic_traffic_management_system_using_infrared_IR_and_Internet_of_Things_IoT

5. Intelligent Cross Road Traffic Management System” by Ahmed S. Salama, IEEE Intelligent Transportation Systems Conference, 2009

https://www.academia.edu/63164894/Smart_Traffic_Management_System

6. Development of a Smart Traffic Light Control System with Real Time Monitoring,IEEE-2020”

https://www.researchgate.net/publication/349533970_Development_of_a_Smart_Traffic_Light_Control_System_With_Real-Time_Monitoring

7. Video Based Vehicle Counting Using Deep Learning Algorithm,IEEE-2020

<https://scihub.se/10.1109/ICACCS48705.2020.9074280>

8. Target Detection of Forward Vehicle Based on Improved SSD,IEEE-2021

https://www.researchgate.net/publication/352098874_Target_Detection_of_Forward_Vehicle_Based_on_Improved_SSD

9.AI Traffic Control System Based on Deep stream and IoT Using NVIDIA Jetson Nano,IEEE-2022

https://www.researchgate.net/publication/363445601_AI_Traffic_Control_System_Based_on_Deepstream_and_IoT_Using_NVidia_Jetson_Nano

[ased_on_Deepstream_and_IoT_Using_NVidia_Jetson_Nano](https://www.researchgate.net/publication/363445601_AI_Traffic_Control_System_Based_on_Deepstream_and_IoT_Using_NVidia_Jetson_Nano)

10. Bi-Directional Dense Traffic Counting Based on Spatio-Temporal Counting Feature and CountingLSTM Network,IEEE-2020

https://www.researchgate.net/publication/342402595_BiDirectional_Dense_Traffic_Counting_Based_on_SpatioTemporal_Counting_Feature_and_Counting-LSTM_Network